

MLFB-Ordering data

6SL3210-1KE27-0AF1



Client order no. : Order no. : Offer no. : Remarks :

Item no. :
Consignment no. :
Project :

Rated data		General tech. specifications		
Input		Power factor λ	0.9	0 0.95
Number of phases	3 AC	Offset factor cos φ	0.9	9
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.9	8
Line frequency	47 63 Hz	Sound pressure level (1m)	72 (dB
Rated current (LO)	64.00 A	Power loss	1.0	2 kW
Rated current (HO)	61.00 A	Filter class (integrated)	Clas	ss A
Output		Ambian	t conditior	20
Number of phases	3 AC	Ambien	t condition	15
Rated voltage	400 V	Cooling	Air cooling	g using an integrated fan
Rated power IEC 400V (LO)	37.00 kW	Cooling of requirement	0.055 m3/	(1,0,1,2,1+3,1,2)
Rated power NEC 480V (LO)	40.00 hp	Cooling air requirement		s (1.942 ft ³ /s)
Rated power IEC 400V (HO)	30.00 kW	Installation altitude	1000 m (3	3280.84 ft)
Rated power NEC 480V (HO)	30.00 hp	Ambient temperature		
Rated current (IN)	68.00 A	Operation		°C (-4 104 °F)
Rated current (LO)	68.00 A	Transport	-40 70 °	°C (-40 158 °F)
Rated current (HO)	58.00 A	Storage	-40 70 °	°C (-40 158 °F)
Max. output current	116.00 A	Relative humidity		
Pulse frequency	4 kHz	Max. operation	95 % RH, d	condensation not permitted
Output frequency for vector control	0 240 Hz			
		Closed-loop control technique		nniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / paramet	erizable	Yes
		V/f with flux current control (FC	C)	Yes
Overload capability		V/f ECO linear / square-law		Yes
Low Overload (LO) 150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time		Sensorless vector control		Yes
		Vector control, with sensor		No
		Encoderless torque control		No

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Torque control, with encoder

No



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			Figure	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP	
Size	FSD	Connections		
Net weight	19.50 kg (42.99 lb)	Signal cable		
Width	200 mm (7.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG	
Height	472 mm (18.58 in)	Line side		
Depth	237 mm (9.33 in)	Version	screw-type terminal	
Inputs / outputs		Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG	
tandard digital inputs		Motor end		
Number	6	Version	Screw-type terminals	
Switching level: 0→1	11 V	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG	
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Screw-type terminals	
ail-safe digital inputs		Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG	
Number	1	Line length, max.	10 m (32.81 ft)	
igital outputs		PE connection		
Number as relay changeover contact	1	Max. motor cable length	Screw-type terminals	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	200 m (656.17 ft)	
Number as transistor	1	Unshielded	300 m (984.25 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Vo Directive 2006/95/EC	
witching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			

Number

1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\mathrm{C}$

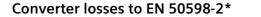


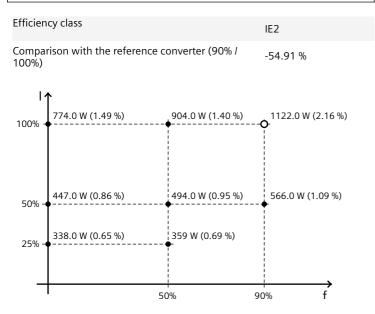
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Figure similar





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values